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Simon Fraser University
Department of Mathematics
Midterm Examination 2
MATH 232
14 November 2005 11:30–12:20

- Please ensure that you sign your exam above to certify your identity. Unsigned exams will not be marked.
- The duration of this exam is 50 minutes.
- DO NOT OPEN this test booklet until told to do so.
- Please check that you have all 6 pages of the exam.
- Do ALL your work in this test booklet. You may use the backside of each page for scrap work.
- The value of each question is shown on the left margins.

Question	Score	Maximum
1		8
2		8
3		8
4		4
5		12
Total		40

1. Let $A = \begin{bmatrix} 1 & 2 & 3 & 1 & 0 \\ 4 & -1 & 3 & 4 & 0 \\ 1 & 3 & 4 & 1 & 0 \\ 2 & 3 & 4 & 4 & 0 \end{bmatrix}$ and suppose a row echelon form of A is

$$B = \begin{bmatrix} 1 & 0 & 0 & 3 & 0 \\ 0 & 2 & 0 & 4 & 0 \\ 0 & 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

[4] (a) Determine a basis for $\text{Row}(A)$.

The non-zero rows of B give a basis for $\text{Row}(A)$.

[4] (b) Determine a basis for $\text{Row}(A^t)$ which consists of rows of A^t .

We note that $\text{Row}(A^t) \cong \text{Col}(A)$. Columns 1, 2, 3 of A are pivot columns so they form a basis for $\text{Col}(A)$. Hence $\left\{ \begin{bmatrix} 1 & 4 & 1 & 2 \end{bmatrix}, \begin{bmatrix} 2 & -1 & 3 & 3 \end{bmatrix}, \begin{bmatrix} 3 & 3 & 4 & 4 \end{bmatrix} \right\}$ forms a basis for $\text{Row}(A^t)$.

2. Let $V = \mathbb{P}_2$. Consider $\mathcal{B} = \{1, 1+t, 1+t+t^2\}$ and $\mathcal{C} = \{1+t+t^2, 1+t, 2\}$ (where the vectors are ordered as given).

[4] (a) Show that \mathcal{B} is a basis for V .

Let's compute $P_{\mathcal{B}}$. It is

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}.$$

The columns of $P_{\mathcal{B}}$ are linearly-independent and span \mathbb{R}^3 as there are 3 pivot columns. Hence, \mathcal{B} is a basis for V .

[4] (b) Find the change of basis matrix $P_{\mathcal{B} \leftarrow \mathcal{C}}$.

The short way is to note that if $\mathbf{x} = \gamma_1 \mathbf{c}_1 + \gamma_2 \mathbf{c}_2 + \gamma_3 \mathbf{c}_3$ then $\mathbf{x} = 2\gamma_3 \mathbf{b}_1 + \gamma_2 \mathbf{b}_2 + \gamma_1 \mathbf{b}_3$. Hence, $[\mathbf{x}]_{\mathcal{B}} = P_{\mathcal{B} \leftarrow \mathcal{C}} [\mathbf{x}]_{\mathcal{C}}$ where

$$P_{\mathcal{B} \leftarrow \mathcal{C}} = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}.$$

The longer way is to bring $[P_{\mathcal{B}} | P_{\mathcal{C}}]$ to $[I | P_{\mathcal{B}}^{-1} P_{\mathcal{C}}]$ using row reduction.

3. Let

$$A(\lambda) = \begin{bmatrix} -\lambda & 1 & 0 & 0 \\ 0 & -\lambda & 1 & 0 \\ 0 & 0 & -\lambda & 1 \\ 0 & 0 & 1 & -\lambda \end{bmatrix}.$$

[4] (a) Show that the determinant of $A(\lambda)$ is $\lambda^2(\lambda^2 - 1)$.

$$\begin{aligned} |A(\lambda)| &= \begin{vmatrix} -\lambda & 1 & 0 & 0 \\ 0 & -\lambda & 1 & 0 \\ 0 & 0 & -\lambda & 1 \\ 0 & 0 & 1 & -\lambda \end{vmatrix} \\ &=_{(R_3 \leftrightarrow R_4)} - \begin{vmatrix} -\lambda & 1 & 0 & 0 \\ 0 & -\lambda & 1 & 0 \\ 0 & 0 & 1 & -\lambda \\ 0 & 0 & -\lambda & 1 \end{vmatrix} \\ &=_{R_4 \leftarrow R_4 + \lambda R_3} - \begin{vmatrix} -\lambda & 1 & 0 & 0 \\ 0 & -\lambda & 1 & 0 \\ 0 & 0 & 1 & -\lambda \\ 0 & 0 & 0 & 1 - \lambda^2 \end{vmatrix} \\ &= \lambda^2(\lambda^2 - 1) \end{aligned}$$

[4] (b) Determine a basis for $\text{Nul}A(-1)$.

$$\begin{aligned}
 A(-1) = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} &\xrightarrow{R_4 \leftarrow R_4 - R_3} \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
 &\xrightarrow{R_2 \leftarrow R_2 - R_3} \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
 &\xrightarrow{R_2 \leftarrow R_2 - R_3} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}
 \end{aligned}$$

Therefore, $\text{Nul}A(-1) = \text{Span} \left\{ \begin{bmatrix} -1 & 1 & -1 & 1 \end{bmatrix}^t \right\}.$

- [2] 4. (a) Using the answers from Question 3, determine the characteristic polynomial of

$$B = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}.$$

The characteristic polynomial is given by $\det(B - \lambda I) = \det A(\lambda) = \lambda^2(\lambda^2 - 1)$.

- [2] (b) Using the answers from Question 3, determine a basis for the eigenspace of B corresponding to the eigenvalue -1 .

The eigenspace of eigenvalue -1 of B is given by $\text{Nul}(B+I) = \text{Nul}A(-1) = \text{Span} \left\{ \begin{bmatrix} -1 & 1 & -1 & 1 \end{bmatrix}^t \right\}$.

5. Let V be a vector space over \mathbb{R} with basis $\{\mathbf{b}_1, \mathbf{b}_2\}$. Let $T : V \rightarrow \mathbb{R}^2$ and $S : V \rightarrow \mathbb{R}^2$ be linear transformations.

[4] (a) Show that $R(\mathbf{x}) = S(\mathbf{x}) + 2T(\mathbf{x})$ is a linear transformation.

$R(\mathbf{x} + \mathbf{y}) = S(\mathbf{x} + \mathbf{y}) + 2T(\mathbf{x} + \mathbf{y}) = S(\mathbf{x}) + S(\mathbf{y}) + 2(T(\mathbf{x}) + T(\mathbf{y})) = S(\mathbf{x}) + 2T(\mathbf{x}) + S(\mathbf{y}) + 2T(\mathbf{y}) = R(\mathbf{x}) + R(\mathbf{y})$.
Similarly, $R(c\mathbf{x}) = S(c\mathbf{x}) + 2T(c\mathbf{x}) = c(S(\mathbf{x}) + 2T(\mathbf{x})) = cR(\mathbf{x})$

[4] (b) Suppose that $T(\mathbf{b}_1) = \mathbf{e}_1$, $T(\mathbf{b}_2) = \mathbf{e}_2$, $S(\mathbf{b}_1) = \mathbf{e}_2$, $S(\mathbf{b}_2) = \mathbf{e}_1$. Show that if $\alpha, \beta \in \mathbb{R}$ are such that $\alpha T(\mathbf{x}) + \beta S(\mathbf{x}) = \mathbf{0}$ for all $\mathbf{x} \in V$, then $\alpha = \beta = 0$.

Plugging in $\mathbf{x} = \mathbf{b}_1$ yields $\alpha T(\mathbf{x}) + \beta S(\mathbf{x}) = \alpha \mathbf{e}_1 + \beta \mathbf{e}_2 = \mathbf{0}$.
By linear independence of $\mathbf{e}_1, \mathbf{e}_2$, we get that $\alpha = \beta = 0$.

[4] (c) For an invertible matrix A , show that $\det(A^{-1}) = 1/\det(A)$.

Since $AA^{-1} = I$, taking determinants yields $\det A \cdot \det A^{-1} = \det I = 1$. Hence, $\det A^{-1} = 1/\det(A)$.